# SEAGUARD® RCM

## **Recording Current Meter**



The new SEAGUARD® RCM series replaces the industry standard RCM 9 and RCM 11 series. It has been completely redesigned from bottom up and employs modern technology in the datalogger section and in the different sensor solutions.

The SEAGUARD® architecture is based on a general datalogger unit and a set of autonomous smart sensors. The datalogger and the smart sensors are interfaced by means of a reliable CANbus interface(AiCaP), using XML for plug and play capabilities. During power-up, each of the sensors that are connected to the bus will report their capabilities and specifications to the datalogger. The datalogger then assembles the information and provides the user with the possibility to configure the instrument based on the present nodes. The solution provides for great flexibility in both use and design of the different elements within the system.

The autonomous sensor topology also gives the sensor designer flexibility and opportunities where each sensor type may be optimized with regard to its operation, each sensor may now provide several parameters without increasing the total system load.

Data storage takes place on a Secure Digital (SD) card. The current capacity for this card type is up to 4GBytes, is more than adequate for most applications.

#### **SEAGUARD®** Recording Current Meter

The SEAGUARD® RCM series is a completely new generation of current meters based on the SEAGUARD® datalogger platform and the ZPulse™ Doppler Current Sensor¹. Modern computer technology combined with advanced digital signal processing provides accurate and detailed measurements with almost unlimited resolution. Optional parameters are available through a new range of smart sensors that include temperature, pressure, conductivity,oxygen, wave and tide. The new SEAGUARD® RCM series come in 300m, 2000m and 6000m depth ranges.

#### SEAGUARD® RCM advantages:

- Large storage capacity on SD card
- Broadband ZPulse™ multi-frequency technology reduces power consumption and improves quality
- Down to 2 second recording interval
- Low current drain
- Smart sensor topology based on a reliable semi-high speed CANbus interface (AiCaP)
- Up to 4 Analog sensor input (0-5V)
- Windows CE based datalogger with TFT based color touch panel for local configuration
- SEAGUARD Studio visualization software
- For use in sea and fresh water
- Real-Time XML Output (optional)

Patent Pending

The SEAGUARD® also has an built-in power calculator which gives an etsimated deployment lenght bases on selected interval, battery type and current drain information, obtained from each smart sensor.

#### **Sensor Capability**

The SEAGUARD® RCM comes standard with the ZPulse™ multi-frequency Doppler current sensor. The new current sensor comprises acoustic pulses of several frequency components to lower the statistical variance in the Doppler shift estimate. The advantage of this is reduced statistical error with fewer pings, providing increased sampling speed and lower power consumption. The new Doppler Current Sensor also incorporates a robust fully electronic compass and a tilt sensor.

The SEAGUARD® RCM may also be delivered with new smart sensor solutions for Temperature, Pressure, Conductivity and Oxygen. All sensors have increased resolution compared with the older models. The temperature sensor also has decreased settling time to utilize the increased sampling speed provided by the SEAGUARD® platform. There is also an analog Turbidity Sensor available for direct connection on the top end plate.



### **Specifications**

Top-end Plate capability: Up to 6 sensors can be fitted onto the

Top-end Plate, of which 4 can be

analog sensors (0-5V)

**Recording System:** Data Storage on SD card  $\geq 4GB$ 

**Storage Capacity:** 

**Battery:** 

Alkaline 3988: 9V. 15Ah (nominal 12.5Ah; 20W

down to 6V at 4°C)

or Lithium 3908: 7V, 35Ah

**Recording Interval:** From 2s, depending on the node

configuration for each instrument

Fixed interval settings or **Recording settings:** 

Customized Sequence setting

**Protocol:** AiCaP CANbus based protocol

**Depth Capacity:** 300m/2000m/6000m

**Platform Dimensions:** 

H: 356mm OD: 139mm 300m version (SW): 2000m version (IW): H: 352mm OD: 140mm 6000m version (DW): H: 368mm OD: 143mm

**External Materials:** 

PET, Titanium, Stainless Steel 316, 300m version:

Durotong DT322 polyurethane

2000/6000m version: Stainless steel 316, Titanium, OSNI

SIL, Durotong DT322 polyurethane

In Water Weight: In Air 7.6 kg 300m version (SW): 2.0 kg2000m version (IW): 14.8 kg 8.5 kg6000m version (DW): 15.7 kg 10.5 kg

**Supply Voltage:** 6-14 Volts **Operating Temperature:** -5 to +50°C

ZPulse<sup>™</sup> Doppler Current Sensor (DCS) Specifications

**Current Speed:** (Vector averaged) 0-300 cm/s Range: Resolution: 0.1 mm/sMean Accuracy:  $\pm 0.15$  cm/s Relative:  $\pm$  1% of reading

Statistic variance (std) 0.3 cm/s (ZPulse mode),

0.45 cm/s 1)

**Current Direction:** 

Range: 0 – 360° magnetic

Resolution:  $0.01^{\circ}$ 

 $\pm 5^{\circ}$  for 0-15° tilt Accuracy:

±7.5° for 15-35° tilt

**Tilt Circuitry:** 

0-35° Range:  $0.01^{\circ}$ Resolution:  $\pm 1.5^{\circ}$ Accuracy:

**Compass Circuitry:** 

 $0.01^{\circ}$ Resolution: Accuracy: ±3°

**Acoustics:** 

Frequency: 1.9 to 2.0 MHz Power: 25 Watts in 1ms pulses

Beam angle (main lobe):

**Installation distance:** 

0.75mFrom surface: From bottom: 0.5m

SEAGUARD Studio Accessories Included:

> SD card: 2 GB Alkaline Battery 3988 Documentation on CD Carry handle 4132

**Optional Accessories:** Carry handle 4032,3965

In-line 40442)/3824A Mooring frame: Bottom 3448R

> Protecting Rods 3783 Sub-surface floats 2211,2212

Battery: Internal Lithium 3908

> Internal Alkaline 3988 Internal Battery Shell 4513 Electrical terminal 4784 AC/DC adapter, lab. use 4908 Real Time licence and collector 4715

Offline Configuration 4811 Analog cable/license 4564/4802 Maintenance Kit 3813/3813A

Tools kit 3986A Vane Plate 3781,3681 Hardcopy Documentation

**Optional Sensors:** 

**Temperature Sensor 4060** 

-4-36°C (32-96.8°F)3) Range: Resolution: 0.001°C (0.0018°F) Accuracy: ±0.03°C (0.054°F) Response Time 63%): < 2 seconds

**Conductivity Sensor 4319** 

Range: 0-7.5 S/mResolution: 0.0002 S/m

Accuracy

Wave:

4319 A: ±0.005 S/m 4319 B: ±0.0018 S/m Response Time:  $<3s^{5)}$ 

Wave and Tide Sensor 4648A

0-400kPa (0-58psia) Pressure: Range: <0,002% FSO Resolution:

±0,04% FSO Accuracy: Sampling rate: 2Hz, 4Hz

Number of samples: 256,512,1024,2048

**Pressure Sensor 4117** 

Resolution: <0.002% FSO Accuracy: ±0.04° FSO

0 - 1000kPa (0 - 145 psia)<sup>4)</sup> 4117A Range: 4117B Range: 0 - 4000kPa (0 - 580 psia)0 - 10000kPa  $(0 - 1450 \text{ psia})^{4}$ 4117C Range: 0 – 20000kPa (0 – 2900 psia) 0 – 40000kPa (0 – 5800 psia)<sup>4)</sup> 4117D Range: 4117E Range: 4117F Range: 0 - 60000kPa (0 - 8700 psia)

**Turbidity Sensor 4112** 

0-5V Analog Output

4112 Range: 0-25 FTU 4112A Range: 0-125 FTU 4112B Range: 0-500 FTU 0-2000 4112C Range: FTU6)

Oxygen Optode 4835/4330 O2-Concentration Air Saturation Measurement Range:  $0-500~\mu M$ 0 - 150%

 $< 1 \mu M$ 0.4 % Resolution: <8 μM or 5%<sup>7)</sup> <5 %<sup>8)</sup> Accuracy: whichever is greater

**Response Time (63%):** 4330F (with fast response foil) <8 sec

4835/4330 (with standard foil) <25 sec

<sup>1)</sup> Based on 300 pings

<sup>2)</sup> In-line Mooring Frame 4044: breaking strength 800 kg

<sup>3)</sup> Extended range available on request.

<sup>4)</sup> Available on request

<sup>5)</sup> Dependent on flow through cell bore

<sup>6)</sup> Sensor is non-linear above 750 FTU

<sup>7)</sup> Requires salinity compensation for salinity < 1mS/cm

<sup>8)</sup> Within calibrated range 0-120%

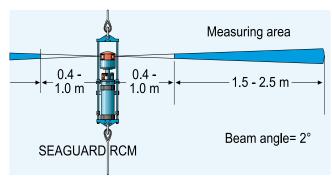
### **Illustrations and Descriptions**

The ZPulse™ Doppler Current Sensor (DCS) is the standard sensor on the SEAGUARD® RCM. The sensor outputs Absolute Current Speed and Direction, Speed in east and north direction, Ping count, and extensive readout of quality control parameters such as Single-ping Standard deviation, Heading, Tilt in X- and Y-direction, and Signal Strength.

The SEAGUARD® RCM utilizes the wellknown Doppler Shift principle as basis for its measurements.



Note! If application requires breaking strength of more than 800 kg, mount the SEA-GUARD® RCM SW in in-line mooring frame 3824A. Remember to change the handles.



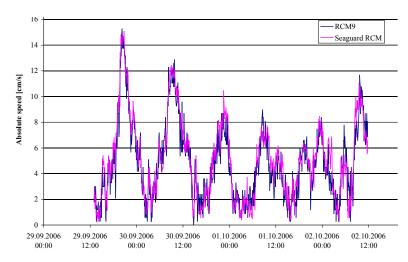
Four transducers transmit short pulses (pings) of acoustic energy along narrow beams (600, 300, 150, or 50 pings in each recording interval). The same transducers receive backscattered signals from scatteres that are present in the beams, which are used for calculation of the current speed and direction.

The scattering particles are normally plankton, gas bubbles, organisms and particles stemming from man-made activity.

To minimize the effect of marine fouling and local turbulence, the ZPulse<sup>TM</sup> DCS starts measuring the horizontal current in an area of 0.4 to 1.0 meter from the instrument, see figure above.

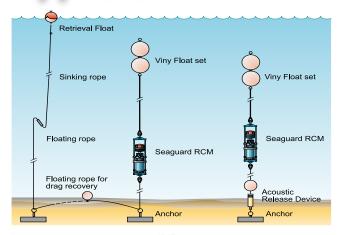
#### Comparing SEAGUARD® RCM with RCM 9

The SEAGUARD® RCM has been tested together with a RCM 9 to compare the measurement results. The deployment was performed during a weekend in a fjord outside Bergen. The graph below shows the absolute speed of both instruments. Pink graph is representing the SEAGUARD® RCM, while blue is representing the RCM 9. The SEAGUARD® was in this test set to transmit 150 ping during each recording interval, while the RCM 9 was set to transmit 300 ping. Although the SEAGUARD® only transmitted half as many pings compared to the RCM 9, the two instruments gave very similar results. Lower ping count reduces power consumption.



Comparision between data measured by a SEAGUARD® RCM (pink) and a RCM 9 (blue). The graph is showing absolute speed measured in a fjord outside Bergen, Norway.

### **Applications**





**SEAGUARD Studio** 

With SEAGUARD Studio you can:

- Import deployment data collected by the SEAGUARD® RCM from a SD card.
- Display configuration setting used in the depoyment.
- Display listed data.
- Possible to show data from several instruments at the same time for comparative studies.
- Export data to Matlab.
- Export data to ASCII text files.
- Print or export graphs in different formats.
- Copy graphs to the clipboard for inclusion into other programs such as Word, Excel or similar.
- Save edited sessions.
- Calculate virtual parameters.

#### **AADI Real Time**

The data message from the instrument is in XML format A user application can access the AADI Real-Time Collector over the Internet or Intranet. Each user application will experience an individual connection to the instrument data due to an queue management system in the collector. One license per SEAGUARD® instrument serves multiple user applications. Including AADI Real-Time Collector, AADI Real-Time Viewer, Style Sheets and example application (See B163)

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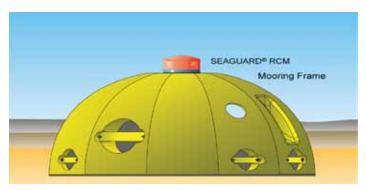
http://www.aadi.no e-mail: info@aadi.no

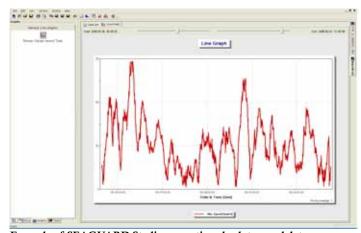


The most common way to use the SEAGUARD® RCM is in an in-line mooring configuration. As it operates under a tilt up to 35° from vertical, it has a variety of in-line mooring applications by use of surface buoy or sub surface buoy. The instrument is installed in a mooring frame that allows easy installation and removal of the instrument without disassembly of the mooring line.

Drop line is conveniently done due to its compact design, low drag force and easy handling. The instrument can be lowered into the sea from a small boat using a simple winch. Data can be stored internally and read after retrieval.

SEAGUARD® RCM can also be used in a bottom frame mooring (non-magnetic).





Example of SEAGUARD Studio presenting absolute speed data measured with a SEAGUARD® RCM.

### **Offline Configuration**

The Seaguard Offline Configuration is a PC application used to create and modify configuration files for the SEA-GUARD<sup>®</sup>. The configuration files can be imported to one or multiple SEAGUARD<sup>®</sup> instruments using a compatible memory card (SDcard).(See TD 275).

Representative's Stamp